

Micro-mouse

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- Goals:

- Build an autonomous robotic "mouse" that negotiates a maze of standard dimensions from a specified corner to its center in the shortest time
- Build a second remote controlled robot for cat/mouse chase game. This robot will be user controlled and faster than the micro-mouse bot.

- Deliverables:

- Microcontroller
- 2 Robot frames
- Software for search algorithms
- Motors and actuators for robot movement

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